

03/09/2024
Friday

MODULE: 05

ROTATION

KINEMATICS OF ROTATION

- Angular displacement, θ in radians.
- Angular velocity, ω
- Angular acceleration, α

$$\omega = \frac{d\theta}{dt} \text{ rad/s}$$

$$\alpha = \frac{d\omega}{dt} \text{ rad/s}^2$$

$$\omega = \frac{2\pi N}{60} \text{ rad/s}$$

N = angular velocity in rpm (revolutions per minute)

(a) For uniformly accelerated angular motion

$$\omega = \omega_0 + \alpha t$$

$$\omega^2 = \omega_0^2 + 2\alpha\theta$$

$$\theta = \omega_0 t + \frac{1}{2}\alpha t^2$$

(b) For uniform angular retardation

$$\omega = \omega_0 - \alpha t$$

$$\omega^2 = \omega_0^2 - 2\alpha\theta$$

$$\theta = \omega_0 t - \frac{1}{2}\alpha t^2$$

Relation between linear ~~acceleration~~ ^{velocity} and angular ~~acceleration~~ ^{velocity}

$$v = \frac{ds}{dt} = r \frac{d\theta}{dt} = r\omega$$

$$v = r\omega$$

Relation between linear acceleration and angular acceleration

$$a = \frac{dv}{dt} = \frac{d(r\omega)}{dt} = r \frac{d\omega}{dt} = r\alpha$$

$$a = r\alpha$$

① The armature of an electric motor, has angular speed of 1800 rpm at the instant when power is cut off. It comes to rest in 6 seconds, calculate the angular deceleration assuming it is constant. How many revolutions does the armature make during this period?

$$N_1 = 1800 \text{ rpm}$$

$$\omega_1 = \frac{2\pi N_1}{60} = 2\pi \times 30 \text{ rad/s}$$

$$\omega_2 = \omega_1 + \alpha t$$

$$0 = 2\pi \times 30 - \alpha \times 6$$

$$\alpha = \frac{2\pi \times 30}{6} = \underline{\underline{31.4 \text{ rad/s}^2}}$$

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② A body accelerates uniformly at 5 rad/s^2 & is found to be rotating at 90 rad/s at the end of 12 seconds. Determine the initial velocity and angle turned during this interval.

$$\alpha = 5 \text{ rad/s}^2$$

$$\omega_2 = 90 \text{ rad/s}$$

$$t = 12 \text{ s}$$

$$\omega_2 = \omega_1 + \alpha t$$

$$90 = \omega_1 + 5 \times 12$$

$$\omega_1 = 90 - 60 = \underline{\underline{30 \text{ rad/s}}}$$

$$\theta = \omega_1 t + \frac{1}{2} \alpha t^2$$

$$= 30 \times 12 + \frac{1}{2} \times 5 \times 12 \times 12$$

$$= 360 + 360 = \underline{\underline{720 \text{ rad}}}$$

③ During the starting phase of computer it is observed that a storage disc which was initially at rest executed 2.5 revolutions in 0.5 s. Assuming that the angular acceleration of motion was uniform. Determine

(a) α and (b) velocity of disc at $t = 0.5 \text{ s}$

$$\omega_1 = 0$$

$$\theta = 2.5 \text{ rev} = 2.5 \times 2\pi = 5\pi \text{ rad}$$

$$t = 0.5 \text{ s}$$

(i) angular acceleration

$$\theta = \omega_1 t + \frac{1}{2} \alpha t^2$$

$$5\pi = 0 + \frac{1}{2} \alpha \times 0.5 \times 0.5$$

$$\alpha = \underline{\underline{125.66 \text{ rad/s}^2}}$$

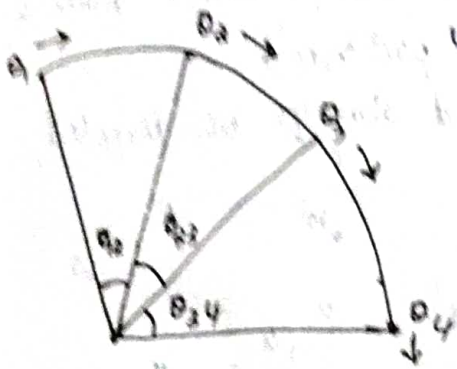
(ii) velocity of disc

$$\omega_2 = \omega_1 + \alpha t$$

$$= 0 + 125.66 \times 0.5$$

$$= \underline{\underline{62.83 \text{ rad/s}}}$$

Q. A wheel accelerates uniformly from rest to a speed of 180 rpm uniformly in 0.4 s. It then rotates at that speed for 2 s before decelerating to rest in 0.3 s. Determine the total revolutions made by the wheel.



$$\omega_0 = 0 \quad N_2 = 180 \text{ rpm}$$

$$\omega_2 = \frac{2\pi N_2}{60} = \frac{2\pi \times 180}{60} = 6\pi \text{ rad/s}$$

$$t_{1-2} = 0.4 \text{ s} \quad t_{2-3} = 2 \text{ s} \quad t_{3-4} = 0.3 \text{ s}$$

$$\omega_2 = \omega_1 + \alpha t_{1-2}$$

$$6\pi = 0 + \alpha \times 0.4 \Rightarrow \alpha = \underline{47.1 \text{ rad/s}^2}$$

$$\theta_{1-2} = \omega_1 t_{1-2} + \frac{1}{2} \alpha t_{1-2}^2 = 0 + \frac{1}{2} \times 47.1 \times 0.4 \times 0.4 = \underline{3.77 \text{ rad}}$$

During θ_{2-3} rotation of wheel, angular acceleration = 0

$$\therefore \omega_3 = \omega_2$$

$$\theta_{2-3} = \omega_2 \times t_{2-3} = 6\pi \times 2 = 12\pi \text{ rad}$$

$$\omega_4 = \omega_3 + \alpha \times t_{3-4} \Rightarrow 0 = 6\pi + \alpha \times 0.3 \Rightarrow \alpha = \underline{-62.8 \text{ rad/s}^2}$$

$$\theta_{3-4} = \omega_3 t_{3-4} + \frac{1}{2} \alpha t_{3-4}^2 = 6\pi \times 0.3 - \frac{1}{2} \times 62.8 \times 0.3^2 = \underline{2.83 \text{ rad}}$$

Total angular displacement

$$\theta = \theta_{1-2} + \theta_{2-3} + \theta_{3-4}$$

$$= 3.77 + 12\pi + 2.83 = 44.28 \text{ rad}$$

$$= \underline{7.05 \text{ revolutions}}$$

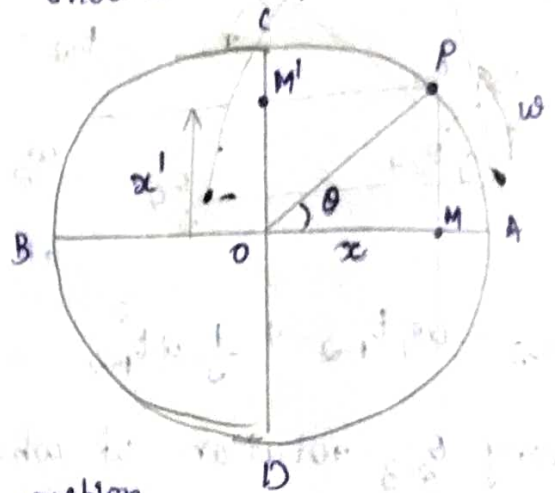
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NOTE

SIMPLE HARMONIC MOTION (SHM)

Conditions for a periodic motion to be simple harmonic.

- The acceleration of the body/particle performing periodic motion should be proportional to the distance of the body/particle from fixed point called the centre of SHM (mean position)
- The acceleration of the body/particle should always be directed towards the mean position.



∴ Let t_p for one oscillation,
 $t = t_p$ & $\theta = 2\pi$

$$2\pi = \omega t_p$$

$$t_p = \frac{2\pi}{\omega}$$

The displacement of M from mean position,

$$OM = x = OP \cos \theta$$

$$x = r \cos \omega t$$

$$v = \frac{dx}{dt} = -r\omega \sin \omega t$$

$$v = r\omega \sin \omega t$$

$$= r\omega \sin \theta = r\omega \frac{PM}{OP} = r\omega \frac{\sqrt{r^2 - x^2}}{r}$$

$$v = \omega \sqrt{r^2 - x^2}$$

Acceleration of M,

$$a = -r\omega^2 \cos \omega t$$

$$a = -\omega^2 x$$

NOTES

- when the time of motion is measured from the mean position
 $x = r \sin \omega t$

- when the time of motion is measured from the extreme position
 $x = r \cos \omega t$

• In both cases,

$$v = \omega \sqrt{r^2 - x^2}$$

$$a = -\omega^2 x$$

- Maximum velocity is at $x=0$ (at mean position)
- Maximum acceleration is at $x=r$ (at extreme position)

$$v_{\max} = \omega \sqrt{r^2 - 0}$$

$$\Rightarrow v_{\max} = r\omega$$

$$a_{\max} = -\omega^2 r$$

⑤ A body moving with SHM has velocities of 10 m/s and 4 m/s at 2 & 4 m distance from mean position. Find the amplitude & time period of the body.

$$v = \omega \sqrt{r^2 - x^2}$$

At $x=2$, $v=10$ m/s

$$10 = \omega \sqrt{r^2 - 2^2}$$

At $x=4$ m, $v=4$ m/s

$$4 = \omega \sqrt{r^2 - 4^2}$$

$$\frac{10}{4} = \frac{\sqrt{r^2 - 4^2}}{\sqrt{r^2 - 2^2}}$$

$$\Rightarrow \frac{100}{16} = \frac{r^2 - 16}{r^2 - 4} \Rightarrow r = 4.28 \text{ m}$$

$$10 = \omega \sqrt{4.28^2 - 4^2}$$

$$\omega = \frac{10}{3.78} = 2.64 \text{ rad/s}$$

$$t_p = \frac{2\pi}{\omega} = \frac{2 \times 3.14}{2.64} = 2.38 \text{ s}$$

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⑥ A body is vibrating with SHM of amplitude 150 mm and frequency 3 cps. Calculate maximum velocity & acceleration of the body

$$r = 150 \text{ mm} = 0.15 \text{ m}$$

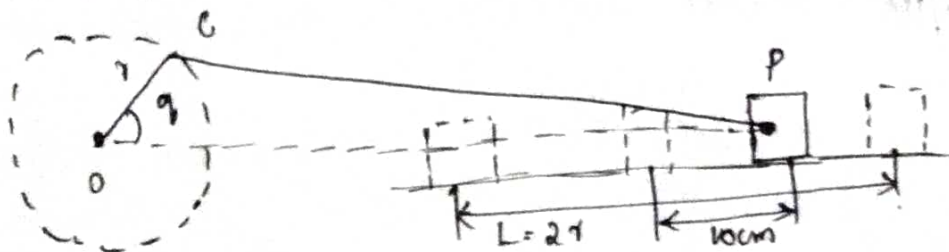
$$f = 3 \text{ cps}$$

$$\omega = 2\pi f = 2\pi \times 3 = 6\pi \text{ rad/s}$$

$$v_{\max} = r\omega = 0.15 \times 6\pi = 2.83 \text{ m/s}$$

$$a_{\max} = \omega^2 r = 2.83 \times 6\pi = 53.3 \text{ m/s}^2$$

⑦ The piston of an IC engine move with SHM. The crank rotates at 420 rpm and stroke length is 40 cm. Find the v and a of piston when it is at a distance of 10 cm from mean position.



Speed of crank = 420 rpm

$$\omega = \frac{2\pi N}{60} = \frac{2\pi \times 420}{60} = 43.98 \text{ rad/s}$$

stroke length $L = 2 \times \text{crank radius}$

$$x = 10 \text{ cm} = 0.1 \text{ m}$$

$$\text{crank radius } r = \frac{L}{2} = \frac{40}{2} = 20 \text{ cm}$$

$$v = \omega \sqrt{r^2 - x^2} = 7.62 \text{ m/s}$$

$$a = \omega^2 x = 193.42 \text{ m/s}^2$$

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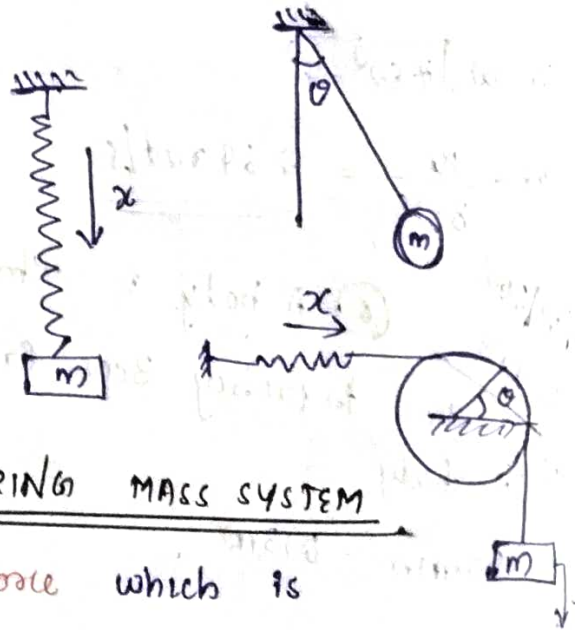
FREE VIBRATIONS

Free vibration :- If the disturbing force is applied just to start the motion and is then removed, leaving it to vibrate by itself.

Force vibration :- If the disturbing force acts at periodic intervals on the system, the system is said to undergo forced vibration.

DEGREE OF FREEDOM

- No. of independent co-ordinates required to define the configuration of the system.
- Constraints to the motion reduce the degree of freedom.



UNDAMPED FREE VIBRATIONS OF SPRING/MASS SYSTEM

- The opposing force is called **spring force** which is proportional to the displacement of the spring.

- Spring force $F \propto x$
 $F = Kx$, $K = \text{stiffness of spring}$

$$\text{Unit} = \text{N/m}$$

EQUATIONS OF FREE VIBRATIONS

$$\therefore \frac{d^2x}{dt^2} + \frac{k}{m}x = 0$$

$$\omega = \sqrt{\frac{k}{m}}$$

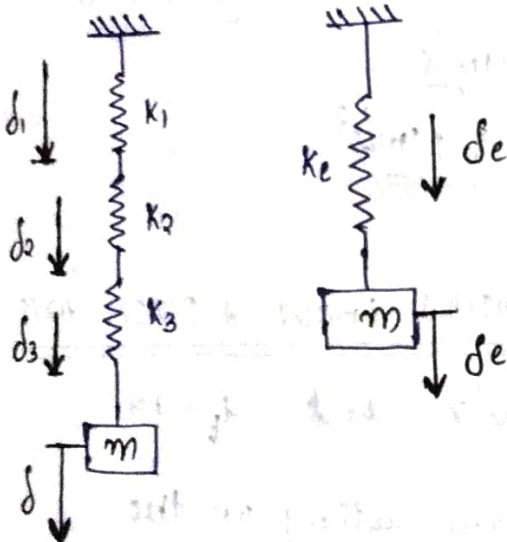
since the system vibrates freely, this frequency is called **natural frequency** & is denoted by ω_0 .

$$\omega = 2\pi f, \quad f = \frac{\omega}{2\pi}$$

$$f_n = \frac{1}{2\pi} \times \sqrt{\frac{k}{m}}$$

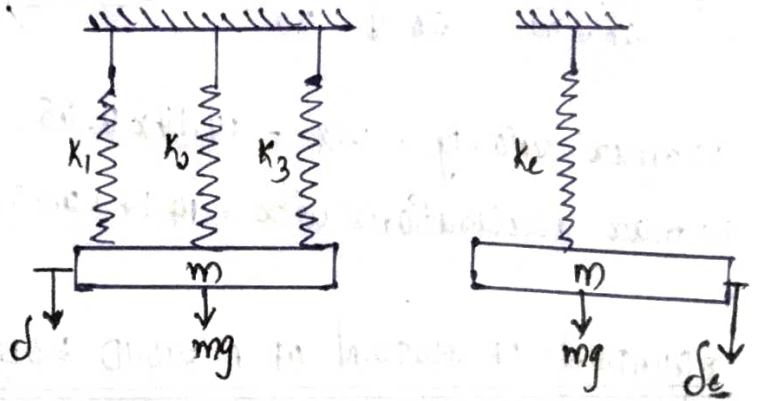
SPRINGS

Springs in series



$$\delta_e = \delta = \delta_1 + \delta_2 + \delta_3$$

Springs in Parallel



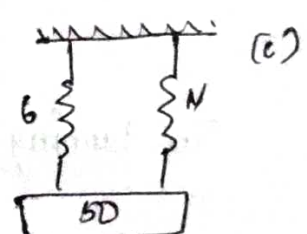
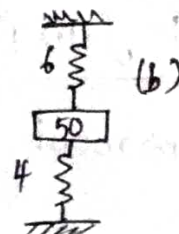
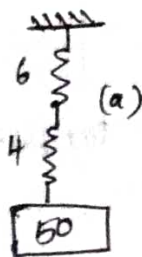
$$\delta_e = \delta$$

$$k_e = k_1 + k_2 + k_3$$

$$\therefore \frac{1}{k_e} = \frac{1}{k_1} + \frac{1}{k_2} + \frac{1}{k_3}$$

⑧ A body of mass 50kg is suspended by two springs of stiffness 4kN/m and 6kN/m as shown in fig(a), (b) and (c). The body is pulled 50mm down from its equilibrium position and then released. Calculate:-

- (i) frequency of oscillation
- (ii) max velocity
- (iii) max acceleration



case 1: Fig (a)

$$\frac{1}{K_e} = \frac{1}{K_1} + \frac{1}{K_2} = \frac{1}{6} + \frac{1}{4} = \frac{10}{24}$$

$$\Rightarrow K_e = \frac{24}{10} = \underline{\underline{2.4 \text{ kN/m}}}$$

$$f = \frac{1}{2\pi} \sqrt{\frac{K}{m}} = \frac{1}{2\pi} \times \sqrt{\frac{2.4 \times 1000}{50}} = \underline{\underline{1.10 \text{ cps}}}$$

$$\omega = 2\pi f = 2\pi \times 1.10 = \underline{\underline{6.93}}$$

(i) max velocity = $\omega x = 6.93 \times 0.05 = \underline{\underline{0.35 \text{ m/s}}}$

(ii) max acceleration = $\omega^2 x = 6.93 \times 0.35 = \underline{\underline{2.4 \text{ m/s}^2}}$

case 2:- Fig (b), Fig (c)

$$K_e = K_1 + K_2 = 4 + 6 = 10 \text{ kN/m}$$

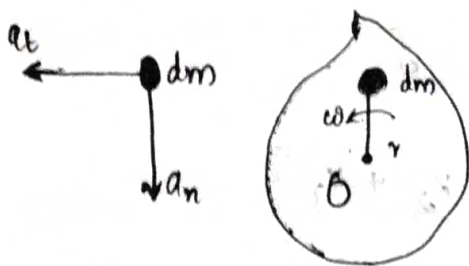
$$f = \frac{1}{2\pi} \sqrt{\frac{K}{m}} = \frac{1}{2\pi} \sqrt{\frac{10 \times 1000}{50}} = \underline{\underline{2.25 \text{ cps}}}$$

$$\omega = 2\pi f = 2\pi \times 2.25 = \underline{\underline{14.14 \text{ rad/s}}}$$

(i) max velocity = $\omega x = 14.14 \times 0.05 = \underline{\underline{0.707 \text{ m/s}}}$

(ii) max acceleration = $\omega^2 x = 14.14 \times 0.05 \times 14.14 = \underline{\underline{9.99 \text{ m/s}^2}}$

EQUATION OF MOTION OF A RIGID BODY ROTATING ABOUT A FIXED AXIS



$$a_n = a_c = \omega^2 r \quad \text{and} \quad a_t = r\alpha$$

The tangential force acting on the elementary mass

$$= \text{mass} \times \text{tangential acceleration} \\ = dm \times (r\alpha)$$

Moment of this force about O = $dm \times (r\alpha) \times r = dm r^2 \alpha$

The turning moment or torque on whole body about O,

$$T = \int dm r^2 \alpha = I \alpha \quad \text{I = mass moment of inertia of body}$$

$$I = \int dm r^2$$

The turning moment or torque $T = I \alpha$

KINETIC ENERGY DUE TO ROTATION

$$\text{Kinetic energy of elementary mass} = \frac{1}{2} dm v^2 = \frac{1}{2} dm \omega^2 r^2 = \frac{1}{2} dm r^2 \omega^2$$

Kinetic energy of whole body,

$$K.E = \int \frac{1}{2} dm r^2 \omega^2 = \frac{1}{2} I \omega^2$$

$$K.E = \frac{1}{2} I \omega^2$$

WORK DONE IN ROTATION

$$\text{Workdone} = T \times \theta$$

WORK-ENERGY EQUATION FOR ROTATION

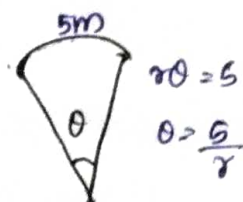
The workdone by a torque acting on a body during an angular displacement is equal to the change in K.E of the body during the same displacement.

⑨ A string 5m long is wound around the axle of a wheel. The string is pulled with a constant force of 250N. The wheel rotates at 300 rpm when the string leaves the axle. Find the moment of inertia of the wheel.

$$\text{Force} = 250 \text{ N}$$

$$\text{Length of string} = 5 \text{ m}$$

$$\omega = \frac{2\pi N}{60} = \frac{2\pi \times 300}{60} = 10\pi \text{ rad/s}$$



$$\text{Change in K.E} = \text{work done}$$

$$\left[\frac{1}{2} I \omega^2 - 0 \right] = T \theta$$

$$= F \times r \times \frac{5}{r} = F \times 5 = 250 \times 5 = 1250 \text{ N}\cdot\text{m}$$

$$\frac{1}{2} \times I \times (10\pi)^2 = 1250 \quad \Rightarrow \quad I = \frac{2500}{(10\pi)^2} = \underline{\underline{2.53 \text{ kg}\cdot\text{m}^2}}$$